## Ditec LCU30H ©HomeLink

Installation manual for the control panel of automations with one or two $24 \mathrm{~V}=\mathrm{motors}$
(translation of the original instructions)


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## Factory settings

## General safety precautions for the user

ATTENTION! Important safety instructions. Please follow these instructions carefully. Failure to observe the information given in this manual may lead to severe personal injury or damage to the equipment.

Keep these instructions for future reference.
WARNING! Disconnect power supply before any cleaning or maintenance operation.
This manual and those for any accessories can be downloaded from www.ditecautomations.com.

These precautions are an integral and essential part of the product and must be supplied to the user. Read them carefully since they contain important information on safe installation, use and maintenance. These instructions must be kept and forwarded to all possible future users of the system - This product must be used only for the specific purpose for which it was designed. Any other use is to be considered improper and therefore dangerous. The manufacturer cannot be held responsible for any damage caused by improper, incorrect or unreasonable use • Avoid operating in the proximity of the hinges or moving mechanical parts. Do not enter within the operating range of the motorized door or gate while it is moving. Do not obstruct the motion of the motorized door or gate, as this may cause a dangerous situation Lock and release the door or gate wings only when the motor is switched off. Do not enter within the action range of the door or gate wing(s) • In case of operation in "hold-to-run" ("dead man") mode, the corresponding command devices must be located so to have direct and complete view of the door or gate during the maneuvers, away from any moving parts, at a minimum height of 1.5 m , and out of reach of the public - The motorized door or gate may be used by children over the age of 8 and by people with reduced physical, sensorial or mental abilities, or lack of experience or knowledge, as long as they are properly supervised or
have been instructed in the safe use of the device and the relative hazards • Children must be supervised to make sure they do not play with the device, nor play or remain in the area of action of the motorized door or gate. Keep remote controls and/or any other command devices out of the reach of children, to avoid any accidental activation of the motorized door or gate • Cleaning and maintenance work intended to be done by the end user must not be carried out by children unless they are supervised. In the event of a product fault or malfunction, turn off the power supply switch. Do not attempt to repair or intervene directly. Any repair or technical intervention must be carried out by qualified personnel. Failure to comply with the above may cause a dangerous situation. To ensure that the system works efficiently and correctly, the manufacturer's indications must be complied with and only qualified personnel must perform routine maintenance on the motorized door or gate. In particular, regular checks are recommended in order to verify that the safety devices are operating correctly • All installation, maintenance and repair work must be documented and made available to the user - To correctly dispose of electrical and electronic equipment, of batteries, and of accumulators, users must take the product to special "recycling centers" provided by the municipal authorities.

## General safety precautions for technical personnel



ATTENTION! Important safety instructions. Please follow these instructions carefully. Failure to observe the information given in this manual may lead to severe personal injury or damage to the equipment. Keep these instructions for future reference. This manual and those for any accessories can be downloaded from www.ditecautomations.com.
This installation manual is intended for qualified personnel only $\bullet$ lnstallation, electrical connections and adjustments must be performed by qualified personnel, in accordance with Good Working Methods and in compliance with the current regulations $\bullet$ Read the instructions carefully before installing the product. Wrong installation could be dangerous - Before installing the product, make sure it is in perfect condition • The packaging materials (plastic, polystyrene, etc.) should not be discarded in the environment or left within reach of children, as they are a potential source of danger - Do not install the product in explosive areas and atmospheres: the presence of inflammable gas or fumes represents a serious safety hazard $\bullet$ Make sure that the temperature range indicated in the technical specifications is compatible with the installation site $\bullet$ Before installing the motorization device, make sure that the existing structure, as well as all the support and guide elements, are up to standards in terms of strength and stability. Verify the stability and smooth mobility of the guided part, and make sure that no risks of fall or derailment subsist. Make all the necessary structural modifications to create safety clearance and to guard or isolate all the crushing, shearing, trapping and general hazardous areas - The motorization device manufacturer is not responsible for failure to observe Good Working Methods when building the frames to be motorized, or for any deformation during use - The safety devices (photocells, safety edges, emergency stops, etc.) must be installed taking into account the applicable laws and directives, Good Working Methods, installation premises, system operating logic and the forces developed by the
motorized door or gate • The safety devices must protect against crushing, cutting, trapping and general danger areas of the motorized door or gate. Display the signs required by law to identify hazardous areas. Each installation must bear a visible indication of the data identifying the motorized door or gate - Before connecting the power supply, make sure the plate data correspond to those of the mains power supply. An omnipolar disconnection switch with a contact opening distance of at least 3 mm must be fitted on the mains supply. Check that there is an adequate residual current circuit breaker and a suitable overcurrent cutout upstream of the electrical installation in accordance with Good Working Methods and with the laws in force • When requested, connect the motorized door or gate to an effective earthing system that complies with the current safety standards • Before commissioning the installation to the end user, make sure that the automation is adequately adjusted in order to satisfy all the functional and safety requirements, and that all the command, safety, and manual release devices operate correctly •

4During installation, maintenance and repair operations, cut off the power supply before opening the cover to access the electrical parts - The protection cover of the operator must be removed by qualified personnel only.

$\triangle$The electronic parts must be handled using earthed antistatic conductive arms. The manufacturer of the motorization declines all responsibility if component parts not compatible with safe and correct operation are fitted • Only use original spare parts for repairing or replacing products - The installer must supply all information concerning the automatic, manual and emergency operation of the motorized door or gate, and must provide the user with the operation and safety instructions.

## EC Declaration of Conformity

EC Declaration of Incorporation
We:
ASSA ABLOY Entrance Systems AB
Lodjursgatan 10
SE-261 44 Landskrona
Sweden
Declare under our sole responsibility that the types of equipment with names:
Ditec LCU30H Control units for swing gates with 1 or 224 V =- operators
Comply with the following directives and their amendments:
2014/35/EU Low Voltage Directive (LVD)
2014/30/EU Electromagnetic Compatibility Directive (EMCD)
2014/53/EU Radio Equipment Drective (RED)
2011/65/EU Restriction of hazardous substances (RoHS 2)
2015/863/EU Restriction of hazardous substances (RoHS 2 Amendment)
Harmonized European standards that have been applied:
EN 61000-6-3:2007 + A1:2011 EN 61000-6-2:2019
EN 60335-1:2012 + A11:2014 + A13:2017 + A 14:2019 EN ISO 13849-1:2015
EN 60529:1991 + A1:2000 + A2:2013 + AC:2016 EN 62233:2008
ETSI EN 300 220-2 V3.2.1
ETSI EN 300 220-1 V3.1.1
ETSI EN 301 489-1 V2.2.3
ETSI EN 301 489-3 V2.1.1
Other standards or technical specifications that have been applied:
EN 12453:2017
The manufacturing process ensures the compliance of the equipment with the technical file.
Responsible for technical file:
Matteo Fino
Business Area PGA
Ditec S.p.A.
Largo U. Boccioni, 1
21040 Origgio (VA)
Italy
Signed for and on behalf of ASSA ABLOY Entrance Systems AB by:
Place
Origgio

Date
2022-03-03


Position
President B.A. PGA

## 1. Safety functions

The Ditec LCU30H control panel has the following safety functions:

- obstacle recognition with force limiting;

The maximum response time of the safety functions is 0.5 s . The reaction time to a faulty safety function is 0.5 s .
The safety functions comply with the standards and performance level indicated below:

$$
\begin{aligned}
& \text { EN ISO 13849-1:2015 Category } 2 \text { PL=c } \\
& \text { EN ISO 13849-2:2012 }
\end{aligned}
$$

The safety function cannot be bypassed either temporarily or automatically. Fault exclusion has not been applied.

## 2. Technical specifications

|  | LCU30H | LCU30HJ |
| :---: | :---: | :---: |
| Power supply | $230 \mathrm{~V} \sim \pm 10 \%, 50 / 60 \mathrm{~Hz}$ | $120 \mathrm{~V} \sim \pm 10 \%, 50 / 60 \mathrm{~Hz}$ |
| Power absorption | 0,6 A | 1,2 A |
| Fuse | F1,6A | F3,15A |
| Motor output | $24 \mathrm{~V}=6 \mathrm{~A} \max (\mathrm{X} 2)$ |  |
| Power supply to accessories 0-1 | $24 \mathrm{~V}=0.5$ A peak / 0,3 A con |  |
| Ambient temperature | $-20^{\circ} \mathrm{C}-+55^{\circ} \mathrm{C}$ |  |
| Storable radio codes | 100 / 200 [see RO $\rightarrow$ MU |  |
| Radio frequency | 433.92 MHz (code ZENRS) or i | MHz (code ZENPRS optional) hasable separately |
| Degree of protection of the container | IP55 |  |
| Product size [mm] | $187 \times 261 \times 102$ |  |
| Operating cycles | Refer to the characteristics | ctuator used. |



NOTE: the given operating and performance features can only be guaranteed with the use of DITEC accessories and safety devices.

### 2.1 Applications



## 3. Installation and electrical connections

- Perforate the relevant points in the bottom part of the box (Fig. 3.1).
- Fix the control panel permanently. You are advised to use round-head screws
(max head $\emptyset 10 \mathrm{~mm}$ ) with a cross (hole centre distance indicated in Fig. 3.2 ).
- Insert the cable glands and corrugated tubes from the lower side of the container.
- Before connecting the power supply, make sure the plate data correspond to those of the mains power supply.
- An omnipolar disconnection switch with a contact opening distance of at least 3 mm must be fitted on the mains supply.
- Check there is an adequate residual current circuit breaker and overcurrent cutout upstream of the electrical system.
- For the power supply, use a H05RN-F 3G1.5 type electric cable. Connect it to the terminals $L$ (brown), N (blue), $\triangleq$ (yellow/green) inside the automation (Fig. 3.3).
NOTE: the maximum permitted wire section is AWG14 (2 mm²).
- In order to comply with the essential requisites of the Standards in force, reclose the cover once the wires have been connected to the terminal.

The connections to the mains power supply and to any possible low voltage wires ( 230 V ) in the section outside the control panel must be made on an independent channel separated from the connections to the command and safety devices (SELV= Safety Extra Low Voltage). The corrugated tubes must enter the control panel by a few centimetres via the holes on the base box.

- Make sure there are no sharp edges that may damage the cables.
- Make sure the mains supply wires ( 230 V ) and the wires of the accessories ( 24 V ) are separated.
- The cables must have dual insulation, be sheathed near the relative connection terminals, and be held in place with ties [A] (not supplied).
- If necessary, fit the clip hinges on the bottom of the box and on the cover lleft or right side, as preferred) (Fig. 3.4).
After making the adjustments and settings, fix the cover in place with the screws supplied (Fig. 3.5).

Fig. 3.1


Fig. 3.2


Fig. 3.3


Fig. 3.5

IP2251EN

### 3.1 Maintenance

The control panel doesn't require any special maintenance.
Make regular checks to ensure the seals on the box and the electrical connections are in good condition.

### 3.2 Standard installation



| Ref. | Description | Cable |
| :---: | :---: | :---: |
| 1 | Transmitter | 1 |
| 2 | Flashing light | $2 \times 1 \mathrm{~mm}^{2}$ |
|  | Antenna lintegrated in the flashing light) | coaxial $50 \Omega$ |
| 3 | Key selector switch | $4 \times 0.5 \mathrm{~mm}^{2}$ |
|  | Digital combination wireless keypad | 1 |
| 4 | Actuator | $2 \times 1.5 \mathrm{~mm}^{2}$ |
|  | Actuator with limit switch | $3 \times 1.5 \mathrm{~mm}^{2}$ |
| 5 | Photocells | $4 \times 0.5 \mathrm{~mm}^{2}$ |
| 6 | Control panel | $3 \mathrm{G} \times 1.5 \mathrm{~mm}^{2}$ |
| A | Connect the power supply to a type-approved omnipolar switch (not supplied), with a contact opening distance of at least 3 mm . <br> Connection to the mains must be via an independent channel, separated from the connections to the command and safety devices. |  |

3.3Standard installation diagram


## 4. Programming

NOTE: pressure on the keys may be quick (less than 2 s) or prolonged (longer than 2 s). Unless specified otherwise, quick pressure is intended. To confirm the setting of a parameter, prolonged pressing is necessary.

### 4.1 Switching the display ON and OFF

The procedure to switch on the display is as follows:
ENTER
$\square$

- press the ENTER key
- the display functioning check starts

- the first level menu is displayed I

The procedure to switch off the display is as follows:

- press the ESC key


NOTE: the display switches off automatically after 60 s of inactivity.

### 4.2 Navigation keys

- The simultaneous pressing of the $\uparrow$ and ENTER keys produces an opening command.

- The simultaneous pressing of the $\downarrow$ and ENTER keys produces a closing command.

- The simultaneous pressing of the $\uparrow$ and $\downarrow$ keys produces a POWER RESET command (power supply interruption and automation restart).

- Keep the UP $\uparrow$ or DOWN $\downarrow$ key pressed to begin fast menu scrolling.
- In some menus, the parameter measurement unit can be viewed by pressing the ENTER key once the value has been displayed.
Example: setting of 10 seconds for parameter OB.



### 4.3 Menu map


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*
Additional configurable parameters available with AT $\rightarrow A A$ is enabled.

## 5. Quick start-up sequences

### 5.1 Selection of automation type

Example of PWR25 automation selection
Set

Example of PWR35 automation selection
Set

NOTE: if no automation is selected (alarm $M \mathbb{M}^{0}$ active) using the values of parameter $Я \bar{\jmath}$ directly.

### 5.2 Configuration of the number of gate wings

Configuration example for a single gate wing
Set


### 5.3 Enabling the configurations

Step-by-step mode without automatic closure (residential use)


Step-by-step mode with automatic closure 1 min (residential use) [standard settings]


Opening mode with automatic closure 1 min (condominium use)

5.4Adding remote controls


### 5.5 Configuration of the limit switches

## Example 1 - Door wing stops against mechanical end stops (standard setting)

Set


Example 2 - Door wing stops against limit switches
Set


With these settings, if an obstacle is detected while opening, the door wing stops and performs a disengagement operation whereas during a closing operation, the door wing reopens.

Example 3 - Door wing stops against mechanical end stops and reverses motion if an obstacle is detected
Set


With these settings, the gate wing stops against its respective mechanical closing end stop and the opening limit switch.
If an obstacle is detected during the opening and before the activation of the stop limit switch, the gate wing stops with a disengagement operation.
If an obstacle is detected during closure and before the activation of the proximity limit switch, the gate wing reopens; once the proximity limit switch has been activated, the gate wing stops against the obstacle.

### 5.6 Configuration of the safety devices

Example 1 - Configuration of the photocells connected to terminals 1-8 and 1-6 [standard settings]
Set


Example 2 - Configuration of the safety edge with safety test simultaneously connected to terminals 1-6 and 1-8
Set


## 6. Application examples

### 6.1 Automations with two swinging gates



When the Ditec LCU3OH control panel is used in applications for automations with two overlapping swinging gate wings, the following connections can be made:

(Fig. 6.1) Installation with mechanical end stops for opening and closure, and without the use of electric limit switches.
(Fig. 6.2) Installation with mechanical end stop for closure, and with the use of electric limit switches (stop during opening and proximity during closure).

### 6.2 Automations with one swinging gate wing



When the Ditec LCU30H control panel is used in applications for automations with one swinging gate wing, the following connections can be made:

(Fig. 6.3) Installation with mechanical end stops for opening and closure, and without the use of electric limit switches.
(Fig. 6.4) Installation with mechanical end stop for closure, and with the use of electric limit switches (stop during opening and proximity during closure).

## 7. Commands

i You are advised to read paragraph 11 for all the details about the possible adjustments.
Command

WARNING: make a jumper for all NC contacts if not used, or deactivate them via the relative menu. Terminals with the same number are equal.

## 7．1 SOFA1－SOFA2 or GOPAVRS self－controlled safety edge

| Command | Function |
| :---: | :---: | :---: | :---: |
| SAFETY TEST |  |


| Description |
| :---: |
| Insert the SOFA1－SOFA2 or GOPAVRS device in the slot for plug－in boards AUX1 or AUX2． <br> If the test fails，an alarm message appears on the display． |
| When selecting AP $\rightarrow$ DG $\rightarrow$ 亏 41 ，connect the output contact of the safety device to terminals 1－6 on the con－ trol panel lin series with the photocell output contact，if installed）． |
| When selecting $\mathrm{AP} \rightarrow$ 昍 $\rightarrow$ 亏 41 ，connect the output contact of the safety device to terminals $1-8$ on the con－ trol panel lin series with the photocell output contact，if installed）． |
| When selecting RP $\rightarrow$ Б日 $\rightarrow \mp 41$ ，connect the output contact of the safety device to terminals $1-6-8$ on the control panel lin series with the photocell output contact， if installed）． <br>  |

## 8．Outputs and accessories

| Value of <br> accessories | Power supply to accessories． <br> Output for power supply to external accessories． <br> NOTE：the maximum absorption of 0.3 A corresponds to the sum <br> of all terminals 1. |
| :--- | :--- | :--- |
| The gate open indicator light（1－13）is not calculated in the 0.3 A |  |
| indicated above，the maximum value considered is 3 W. |  |


| Output | Value of accessories | Description |
| :---: | :---: | :---: |
|  | ZENRS ZENPRS | The control panel is fitted with a housing for modules of the ZENRS radio receiver type ( 433.92 MHz ). <br> Can be replaced with a radio receiver module of the ZENPRS type ( 868.35 MHz ). <br> The operating mode is selected via $B[\rightarrow R M$. <br> When using slot-in radio boards, remove the RDX module. The display will show RI. <br> WARNING: the modules must be inserted and removed with the power supply disconnected. |
| COM | BIXMR2 | COM - This allows the functioning configurations to be saved using the function ' $\lrcorner F \rightarrow \bar{J} v$ '. <br> The saved configurations can be recalled using the function $\bar{J} F$ $\rightarrow$ R [. |
|  |  | COM - The storage module allows the remote controls to be stored. If the control panel is replaced, the storage module being used can be inserted in the new control panel. <br> WARNING: the storage module must be inserted and removed with the power supply disconnected, and paying attention to the positioning direction. |
| $\begin{aligned} & \text { BAT } \\ & \begin{array}{\|l\|l\|} \hline \because & \square \\ \hline \because & \square \\ \hline \end{array} \end{aligned}$ | SBU | BAT - Battery-powered operation. <br> The batteries are kept charged when the power supply is on. If the power supply is off, the panel is powered by the batteries until the power is re-establish or until the battery voltage drops below the safety threshold. The control panel turns off in the last case. Warning: the batteries must always be connected to the control panel for charging. Periodically check the efficiency of the batteries. <br> NOTE: the operating temperature of the rechargeable batteries is from $+5^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}$. <br> For advanced control of battery-powered operation, refer to the menu EM. |

## 9. Jumper setting

| Jumper | Description | OFF | ON |
| :--- | :--- | :--- | :--- | :--- |
| JR1 | Display mode selection. | Display mode. <br> Only the values and parame- <br> ters present can be displayed. | Maintenance mode. <br> Only the values and parame- <br> ters present can be displayed <br> and modified. <br> Activated maintenance mode <br> is indicated by the permanent <br> switching on of the right-hand <br> point on the display. |

## 10. Adjustments

NOTE: depending on the type of automation and control panel, some menus may not be available.

### 10.1 Main menu

| Display | Description |
| :---: | :---: |
|  | AT - Automatic Configurations. <br> The menu allows you to manage the automatic configurations of the control panel. |
|  | BC - Basic Configurations. <br> The menu allows you to display and modify the main settings of the control panel. |
|  | BA - Basic Adjustments. <br> The menu allows you to display and modify the main adjustments of the control panel. NOTE: some settings require at least three operations before they are set correctly. |
|  | RO - Radio Operations. <br> The menu is used to manage the radio functions of the control panel (alarm management, diagnostics enabling, FW updating). |
|  | SF - Special Functions. <br> The menu allows you to set the password and manage the special functions in the control panel. |
|  | CC - Cycles Counter. <br> The menu allows you to display the number of operations carried out by the automation and manage the maintenance interventions. |
| $E 111$ | EM - Energy Management. <br> The menu allows you to display and modify the energy saving settings and adjustments (Green Mode and battery management). |
|  | AP - Advanced Parameters. <br> The menu allows you to display and modify the advanced settings and adjustments of the control panel (limit switch mode, selection of devices connected to the terminals, disengagement duration adjustments, flashing light adjustments, etc.). |

NOTE: some settings require at least three operations before they are set correctly.

From the main menu you can access the second level menu as follows:


After confirming the selection, you access the second level menu.
For each function of the main menu, there are also additional configurations that can be viewed by enabling the $Я$ function (see the following paragraph).

NOTE: to check if the parameters have actually been modified, quit the relative parameter and then access it again. The modifications will take effect from the next operation.

### 10.2Second level menu - AT (Automatic Configurations)

AS - Automation selection
This selection pre-sets the type of motor and a sub-set of parameters
linked to the kinematic mechanism of the automation for a standard
installation.
See "Selection of automation type", paragraph 10.2.1.
Each parameter can still be modified when necessary.
10.2.1 Selection of automation type $Я \uparrow \rightarrow$ คَ and specific default settings

|  | Model | R1-R2 <br> Thrust <br> obsta- <br> cles and <br> current | VA VC <br> Speed during opening and closure | $\underset{\substack{\text { Learning } \\ \text { speed }}}{\text { VR }}$ | $\begin{aligned} & \text { PO-PC } \\ & \text { Ap- } \\ & \text { proach } \\ & \text { speed } \end{aligned}$ | TA Acceleration time during opening | $\begin{aligned} & \text { TQ } \\ & \text { Accel- } \\ & \text { eration } \\ & \text { time } \\ & \text { during } \\ & \text { enosure } \end{aligned}$ | $\begin{gathered} \text { VM } \\ \text { Ramp } \\ \text { start-up } \\ \text { speed } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 | оввізвн | 50 | 24 | 18 | 07 | 2 | 3 | 03 |
| 回己 | ARCBH | 70 | 14 | 10 | 06 | 2 | 3 | 03 |
| 03 | FACIL3H | 50 | 12 | 10 | 05 | 2 | 3 | 03 |
| 84 | LUXозвн-4BH | 40 | 16 | 12 | 06 | 1 | 2 | 10 |
| 05 | PWR25H | 50 | 18 | 10 | 05 | 2 | 3 | 03 |
| 05 | PWR35H | 50 | 20 | 12 | 06 | 2 | 3 | 03 |
| Q | PWR40H | 40 | 22 | 15 | 06 | 1 | 2 | 10 |

### 10.3Second level menu - BC (Basic Configurations)

AC - Enabling of automatic closure
ON - Enabled
10.3.1 Additional BC level parameters that can be configured lavailable with $\boldsymbol{T} T \rightarrow$ 月月 enabled)
Description

### 10.4Second level menu - BA (Basic Adjustment)



NOTE: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.
10.4.1 Additional BA level parameters that can be configured lavailable with $\uparrow T \rightarrow$ ค月 enabled)
DT - Adjustment of obstacle recognition time [s/100]
10-Minimum
60-Maximum

NOTE: the parameter is adjusted in hundredths of a second. | ST - Adjustment of start time [s] |
| :--- |
| 0.5 - Minimum |
| 3.0 - Maximum |



### 10.5Second level menu - RO (Radio Operations)



WARNING: selecting MU $\rightarrow$ (200 remote controls), the configurations $U 1$ and $U$ 己 saved with the $\bar{\zeta} F \rightarrow \bar{\zeta} V$ command will be lost. This also applies for the last configuration reloaded with RL. In addition, new configurations cannot be saved on $\cup 1$ and $U$ ?
RK - Menu navigation using remote control keyboard
ON - Enabled
OF - Disabled
With the display turned off, quickly type in the sequence of keys (3) (3) (2)
1 from the stored remote control you want to use.
Make sure all the CH keys are stored.
WARNING: during navigation with a remote control keyboard ALL the stored
remote controls are inactive.
To make viewing and adjustment easier lavoiding the need to continuously
press the remote control), press the UP $\uparrow$ or DOWN $\downarrow$ key once to begin
slowly scrolling through parameters.
This scrolling movement is faster if the UP $\uparrow$ or DOWN $\downarrow$ key is pressed twice.
To stop the scrolling, press ENTER.
To confirm your choice of parameter, press ENTER again.
To test any new setting, switch off the display and issue an opening command
using key (3).
Navigation using a remote control keyboard is automatically disabled after 4
minutes of inactivity or by setting RK $\rightarrow \square F$.

### 10.5.1 Additional BO level parameters that can be configured lavailable with $\boldsymbol{T} \rightarrow$ ค月 enabled)




### 10.6Second level menu - SF (Special Functions)

Sisplay

## 10．6．1 Additional SF level parameters that can be configured lavaila－

 ble with $\cap T \rightarrow$ ค $\boldsymbol{T}$ enabled）|  | Display | Description |
| :---: | :---: | :---: |
|  | $\square$ | SP－Setting the password <br> NOTE：this can only be selected when the password is not set． <br> Setting the password prevents unauthorised personnel from accessing selections and adjust－ ments．You can delete the set password by selecting the sequence $J R 1=0 \mathrm{~N}, \mathrm{JR} 1=0 \mathrm{FF}, \mathrm{JR} 1=0 \mathrm{~N}$ ． |
|  |  | IP－Inserting the password <br> NOTE：this can only be selected when the password is set． <br> When the password is not inserted，you can access the display mode regardless of the selec－ tion made with JR1．When the password is inserted，you can access in maintenance mode． |
|  | $E 1$ | EU－Deletion of user configurations and last configuration set in the storage module ENTER <br> ENTER ${ }^{100} 0_{0}^{0} \rightarrow$ $\rightarrow$ H＇ <br> （1）2＂ <br> （2） 2 |
|  |  | AL－Alarm counter <br> Used to view，in sequence，the counters of alarms that have been triggered at least once （alarmp code д亠巾．number of times triggered）． <br> With |
|  | $111$ | AH－Alarm log <br> Used to view in sequence，alarms that have been triggered（maximum 20）． With ${ }^{\circ}$ <br> The display shows the alarm number and code，alternated．The highest number corresponds to the most recent alarm and the lowest number（ 0 ）corresponds to the oldest alarm． |
|  |  | AR－Alarm reset <br> Resets all the alarms in the memory（counters and log）． <br> ENTER $\rightarrow$ $\square$ K <br> （1）2＂ <br> NOTE：when the installation has been completed，you are advised to delete the alarms in order to facilitate future checks． |
|  | $i N 1$ | IM－Motor current visualisation Selecting M 1，the display will show the current absorbed by motor 1. Selecting M己，the display will show the current absorbed by motor 2 ． |
|  |  | UP－Firmware update <br> Activates the card bootloader in order to update the firmware through AMIGO software and USBPROG interface <br> ENTER $\rightarrow$ $\square$ K <br> （1）2＂ |

## 10．7Second level menu－CC（Cycles Counter）

|  | Display | Description |
| :---: | :---: | :---: |
| $0$ |  | CV－Display of total operations counter |

Display

### 10.7.1 Additional CC level parameters that can be configured lavailable with $\cap T \rightarrow$ ЯЯ enabled)

|  | Display | Description | Selections available |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & \frac{1}{む} \\ & \frac{1}{5} \\ & \frac{0}{2} \end{aligned}$ | $[\square$ | CA - Setting the maintenance alarm (factory setting - alarm deactivated: 0.00 You can set the required number of operations (regarding the partial operations signalling the maintenance alarm. <br> When the set number of operations is reached, the alarm message app display l' $\boxed{\square}$.Example: <br> Setting the maintenance alarm after 700 operations (00) (07) (00) | 0. 00). <br> counter) for <br> ears on the |
|  | $1$ | OA - Selecting maintenance alarm display mode <br> 00 - Visualisation on display (alarm message $V^{\prime}$ ( ${ }^{\prime}$ ) <br> 01 - Visualisation on flashing light (with the automation idle, 4 flashes are made and then repeated every hour) and on display (alarm message l' (7). <br> 02 - Visualisation on "open gate" indicator light lwith the automation closed, 4 flashes are made and then repeated every hour) and on display (alarm message l' [ [ |  |
|  | $19$ | ZP - Reset of partial operations counter <br> ENTER <br> $\stackrel{\circ}{\mathrm{O}_{2}^{\circ}} \rightarrow$ $\square$ <br> For correct functioning, you are advised to reset the partial operations counter: <br> - after maintenance work; <br> - after setting the maintenance alarm interval. |  |

### 10.8Second level menu - EM (Energy Management)

|  | Display | Description | Selections available |
| :---: | :---: | :---: | :---: |
| $\frac{\sum}{1 I}$ |  | PV - Solar panel power supply (panels not supplied) <br> ON - Enabled <br> OF - Disabled |  |

Description
Selections available
LB - Indication that batteries are almost flat
00 - Visualisation on display (alarm message 马 $\pi^{3}$ )
01 - Visualisation on flashing light (with the automation idle, 2 flashes are made and then repeated every hour) and on display (alarm message $\frac{\square}{\square}$ )
02 - Visualisation on "open gate" indicator light (with the automation closed, 2 flashes are made and then repeated every hour) and on display (alarm message 召 ( )

10.8.1 Additional EM level parameters that can be configured lavailable with $T \rightarrow$ คЯ enabled)
Display

### 10.9 Second level menu - AP (Advanced Parameters)

|  | Display | Description | Selections available |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | FA - Selection of opening limit switch mode <br> NO -None <br> SX - Stop limit switch (after activation, the gate wing stops its movement) <br> PX - Proximity limit switch (after activation, the gate wing continues as <br> far as the end stop and any obstacle is considered a stop) <br> RA - Deceleration limit switch lafter activation, the gate wing slows down its movement) | $\begin{array}{ccc} A 1 \\ 1 & 1 \\ M & 1 \end{array}$ |  |
| ¢ |  | FC - Selection of closing limit switch mode <br> NO - None <br> SX - Stop limit switch (after activation, the gate wing stops its movement) <br> PX - Proximity limit switch (after activation, the gate wing continues as far as the end stop and any obstacle is considered a stop) <br> RA - Deceleration limit switch lafter activation, the gate wing slows down its movement) |  | $\begin{aligned} & 1 \\ & -2 \\ & 1 \end{aligned}$ |
| - |  | D6 - Selection of device connected to terminals 1-6 <br> NO - None <br> SE - Safety edge lif contact 1-6 opens, there is a disengagement of 10 cm after the stop) <br> S41 - Safety edge with safety test lif contact 1-6 opens, after the stop there is a disengagement of a duration depending on the selection AP $\rightarrow$ DE <br> PH - Photocells <br> P41 - Photocells with safety test | $\begin{array}{ll} 1 & 1 \\ 19 & 1 \\ -7 & 71 \\ \square & 11 \end{array}$ |  |

Description
Display

| D8 - Selection of device connected to terminals $1-8$ |
| :--- |
| NO - None |

SE - Safety edge NOTE: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

### 10.9.1 Additional AP level parameters that can be configured lavailable with $\cap T \rightarrow$ คЯ enabled)

Display

|  | Display | Description | Selections available |
| :---: | :---: | :---: | :---: |
|  |  | LG - Switch-on time for independently commanded courtesy light [s] To enable this parameter, set at least one of the selections $B A \rightarrow E D$ or BR $\rightarrow$ F F as a courtesy light. <br> It is set with different intervals of sensitivity. <br> NO - Disabled <br> - from 01" to 59" with intervals of 1 second <br> - from $1^{\prime}$ to $2^{\prime}$ with intervals of 10 seconds <br> - from 2 ' to $3^{\prime}$ with intervals of 1 minute <br> ON - Switched on and off with remote control <br> NOTE: the switching on of the light does not depend on the start of an operation, but can be commanded separately using the special remote control key. |  |
|  |  | PT - Fixed partial opening <br> ON - Enabled <br> OF - Disabled <br> If ON, a partial opening command given on the partial opening position is ignored. With contact 1-20 closed (for example with the timer or manual selector), the gate will partially open. If it is then fully opened (command 1-3) and reclosed leven with automatic closure), it will stop at the partial opening position. | Miv |
|  |  | $D E$ - Disengagement duration if an edge is triggered [s] <br> Regulates the duration of the disengagement when an edge lactive or passive) is triggered during opening or closure. In the case of gates with two wings, it acts on both wings. <br> 00 - Deactivated |  |
|  |  | DO - Duration of disengagement on stop during opening [s/100] <br> Regulates the duration of the disengagement on the mechanical opening stop. <br> 00 - Disabled <br> 99 - Maximum <br> NOTE: not active if $F A \rightarrow{ }^{\circ} \%$ |  |
|  |  | DC - Duration of disengagement on stop during closure [s/100] <br> Regulates the duration of the disengagement on the mechanical opening stop. <br> 00 - Disabled <br> 99 - Maximum <br> NOTE: not active if $F[\rightarrow \bar{J} K$ |  |
|  |  | OT - Selection of type of obstacle <br> 00 - Overcurrent or gate stopped <br> 01 - Overcurrent <br> 02 - Door stopped |  |
|  |  | CR - Stroke estimate correction [\%] DO NOT USE (diagnostic purposes only) |  |
|  | $\text { E } 11$ | SM - Selection of operating mode of device connected to terminals 1-6 <br> 00 - During the operation, the opening of the safety contact stops the movement (with disengagement if $75 \rightarrow 5 E / 541$ ). <br> 01 - During the operation, the opening of the safety contact stops the movement (with disengagement if $75 \rightarrow \overline{5} 5 / 541$ ). When the contact closes again, the operation is resumed. <br> 02 - During the operation, the opening of the safety contact stops the movement (with disengagement if $75 \rightarrow 5 E / 541$ ). <br> When the contact closes again, an opening operation is performed. <br> 03 - During the closing operation, the opening of the safety contact reverses the movement. During the opening operation, the safety device is ignored. <br> 04 - During the opening operation, the opening of the safety contact stops the movement (with disengagement if IG $\rightarrow$ ЈE / Ј 41 ). When the contact closes again, the interrupted opening operation is resumed. During the closing operation, the safety device is ignored. <br> 05 - During the closing operation, the opening of the safety contact stops and reverses the movement. During the opening operation, the opening of the safety contact stops the movement (with disengagement if $\mathbb{I} G \rightarrow \bar{J}$ / $/ 541$ ). |  |

Description
system and automatic HS ramps [ ${ }^{\circ} \mathrm{C}$ ] for NIO electronic anti-freeze
This value does not refer to the ambient temperature, but to the internal
control panel temperature.

## 11. Signals visualised on the display

NOTE: depending on the type of automation and control panel, certain visualisations may not be available.

### 11.1 Display of automation status



NOTE: the automation status display mode is only visible with Display visualisation mode set to 02


| Display | Description |
| :---: | :---: |
| 11 | Automation stopped in intermediate position |
| $\begin{array}{ll} 1 \\ V & \hat{V} \end{array}$ | Automation closing |


| Display | Description |
| :---: | :---: |
| - | Automation in partial opening |
| -1 |  |
| - |  |
|  |  |

## 11．2 Display of safety devices and commands

NOTE：the safety device and command display mode is only visible with Display visualis－ ation mode set at 01 or 03 ．

| AP \＃ |  |  |  |
| :---: | :---: | :---: | :---: |
| Display | Description | Display | Description |
| $1-\square$ | 1－2－Automatic closing activation com－ mand |  | 1－6－Safety device with opening and clos－ ing stop |
| 1－7 | 1－3－Opening command | $\bigcirc 1$ | S1．－Detection of stop during closure－ motor 1 |
| 1－4 | 1－4－Closing command | I | S．1．－Detection of stop during closure－ motor 2 |
| $1-\mathrm{L}$ | 1－5－Step－by－step command |  | 1－8－Safety with closing reversal |
| $\square]$ | P3－Partial opening command． | $\square$ | 1－9－STOP command |
| $3 \square$ | 3P－Opening command with operator present |  | 68 －Partial opening command |
| $-1 \square$ | $4 \mathrm{P}-\mathrm{Closing}$ command with operator present | 「こ. | S2．－Detection of stop during opening－ motor 1 |
|  | RX－Radio reception lof any memorised key of a transmitter present in the memory） | E. | S．2．－Detection of stop during opening－ motor 2 |
|  | NX－Radio reception lof any non－memo－ rised key） |  | 00．－Reaching of obstacle detection limit during opening－motor 1 |
| 等年 | NOTE：with the selection $A P \rightarrow \rrbracket \bar{\zeta} \rightarrow \square 1$ ，it is also visualised when a command is received from a non－stored transmitter． | ■. | 0．0．－Reaching of obstacle detection lim－ it during opening－motor 2 |
| $[\because$ | EX－Rolling－code radio reception out of sequence | $\Gamma$ | OC．－Reaching of obstacle detection limit during closing－motor 1 |
| $[\square$ | EP－Radio reception not complying with the parameter configuration $尺 \square \rightarrow E P$ | T.L. | O．C．－Reaching of obstacle detection lim－ it during closing－motor 2 |
| L | CX－Command received from AUX1 board | $F_{1}$ | RV－Enabling／disabling of built－in radio receiver via RDX |
|  | FC．－Closure limit switch－motor 1 | M1戓 | MQ－Learning operation of mechanical end stops in progress |
| F. F | F．C．－Closure limit switch－motor 2 | 1 | HT－Heating of the motors（NIO function） in progress |
| $F F$ | FA．－Opening limit switch－motor 1 | L | JR1－Variation of the JR1 jumper status |
| $F .7$ | F．A．－Opening limit switch－motor 2 |  | 1C－Closing operation 11 gate wing at a time） |

### 11.3 Visualisation of alarms and faults

!WARNING: the visualisation of alarms and faults is possible with any visualisation selection. The signalling of alarm messages takes priority over all other displays.

| Type of | Description | Select a type of automation from the AT |
| :--- | :--- | :--- |
| alarm |  |  |

Thene

| Type of <br> alarm | Description | Check battery voltage. <br> Replace battery. |
| :--- | :--- | :--- |

## 12. Troubleshooting

| Problem | Possible cause | Alarm signalling | Operation |
| :---: | :---: | :---: | :---: |
| The control panel does not switch on | No power supply. |  | Check the power supply cable and the relative wiring |
|  | Overload on output 0-1 |  | Disconnect any loads connected to terminal 1 |
| The automation does not open or close. | No power. |  | Check power supply cable. |
|  | Short circuited accessories | 15 | Disconnect all accessories from terminals 0-1 la voltage of $24 \mathrm{~V}=$ must be present) and reconnect them one at a time. Contact Technical Service |
|  | Blown line fuse. |  | Replace fuse. |
|  | Safety contacts are open. | $\begin{aligned} & 1-61-8 \\ & 68 \end{aligned}$ | Check that the safety contacts are closed correctly (NC). |
|  | Safety contacts not correctly connected or self-controlled safety edge not functioning correctly. | $\begin{aligned} & \text { RO } 1-6 \\ & R 11-8 \\ & R 368 \end{aligned}$ | Check connections to terminals 6-8 on control panel and connections to the self-controlled safety edge. |
|  | Photocells activated. | 1-61-8 | Check that the photocells are clean and operating correctly. |
|  | The automatic closure does not work. |  | Issue any command. If the problem persists, contact Technical Service |
|  | Motor fault | MBML | Check motor connection, if the problem persists, contact Technical Service. |
| The external safety devices are not activated. | Incorrect connections between the photocells and the control panel. |  | Check that $1-6 / 1-日$ is displayed Connect NC safety contacts together in series and remove any jumpers on the control panel terminal board |
|  |  |  | Check the $A P \rightarrow$ DG and $A P \rightarrow \mathbb{B}$ setting |
| The automation opens/closes briefly and then stops | There is a presence of friction. | MI | Manually check that the automation moves freely and check the $\uparrow 1 / 尺$ R adjustment. Contact Technical Service |


| Problem | Possible cause | Alarm <br> signalling |
| :--- | :--- | :--- |
| The remote control <br> has limited range and <br> does not work with the <br> automation moving | The radio transmission is im- <br> peded by metal structures and <br> reinforced concrete walls. |  |
| The remote control <br> does not work | No storage module or incorrect <br> storage module. |  |

Install the antenna outside.
Replace the transmitter batteries.

Switch the automation off and plug in the correct storage module.
Check the correct memorisation of the transmitters on the built-in radio. If there is a fault with the radio receiver that is built into the control panel, the remote control codes can be read by removing the storage module

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